# EtherCAT Setup DX-200 Version 1.0

Scott Smith scott.smith@motoman.com September 30 2014

# DOCUMENT REVISION INFORMATION

Date	Version Number	Document Changes
9/30/14	1.00	Initial version

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## LAB SETUP

### HARDWARE REQUIREMENTS

ltem #	Part Number	Description
1		AB3617 EtherCAT Slave Module
2		
3		
4		

#### SOFTWARE REQUIREMENTS

ltem #	Part Number	Description
1		
2		

#### SUPPORTING DOCUMENTATION

ltem #	Part Number	Description
1		ME00107EN-02 Field Bus PCI Instruction Manual
2		
3		

# TWIN CAT SETUP

## ADD ROBOT TO THE ETHERCAT NETWORK

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- 1. Right click on "IO DEVICES"
- 2. Scan the network
- 3. Select the EtherCAT interface
- 4. Press OK

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- 5. While scanning the network, the ECAT master will prompt you to load the description that is stored inside the AnyBus board.
- 6. Select YES



7. Select YES when prompted to SCAN FOR BOXES

#### VERIFY COMMUNICATION

#### Activate FREE RUN mode

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ai [] Ferm 1 (EK1200) □ • • Box 3 (Arwbus-5)		
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Input byte 0007	Actual State: DP Counter Cyclic Queued	
	Init Pre-Op Sate-Op Op Send Frames 14000 + 980	
- OT Input byte 0010	Clear CRC Clear Frames Lost Frames 0 + 0	
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- Of Input byte 0013		
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In FREE RUN mode, you can verify proper communication state

#### Write data to the robot in FREE RUN mode



Read data from the robot in FREE RUN mode

